

自動駕駛 ROS 開發使用 課程模組 軟硬體清單 -

(Machine #1 & 2) LG SVL Simulator

Software:

Git 2.31.0

Linux Ubuntu 16.04 or 18.04

ROS Kinetic Kame and ROS Lunar Loggerhead

Hardware:

Multicore i7 CPU and above

16GB+ main memory

Nvidia GPU GTX series (e.g., GTX 1080) and above